

Static Analysis of OpenStream Programs

Using polyhedral techniques to analyze interesting language subsets

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Solution(s) for high-level parallel programming?

- Static or dynamic?
- Language constructs or libraries?
- Expressiveness: deterministic (no data races) or deadlock-free?
- How to represent communications and memories? Concurrency?
- Can static optimization help runtime optimizations?
Buffer sizes, granularity, mapping, ...

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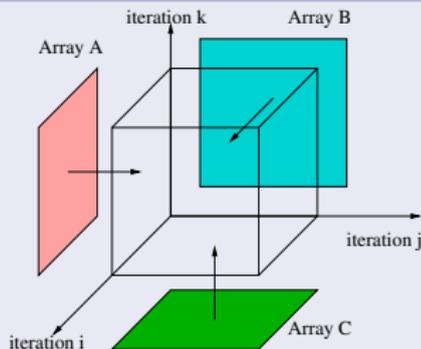
Many approaches:

- “Lower”-level: MPI, OpenCL, Lime, ...
- Runtime-based: Kaapi, StarPU (with task dep. as in OpenMP 4.0).
- (A)PGAS languages: Co-Array Fortran, UPC, Chapel, X10, ...
- “Dataflow” languages: KPN, SDF, CSDF, SigmaC, OpenStream, ...

Multi-dimensional affine representation of loops and arrays

Matrix Multiply

```
int i, j, k;
for(i = 0; i < n; i++) {
  for(j = 0; j < n; j++) {
S:    C[i][j] = 0;
      for(k = 0; k < n; k++) {
T:    C[i][j] += A[i][k] * B[k][j];
      }
  }
}
```



Polyhedral Description

Omega/ISCC syntax

```
Domain := [n]->{S[i][j]: 0<=i,j<n; T[i][j][k]: 0<=i,j,k<n};
```

```
Read := [n]->{T[i][j][k]->A[i][k]; T[i][j][k]->B[k][j];
             T[i][j][k]->C[i][j]};
```

```
Write := [n]->{S[i][j]->C[i][j]; T[i][j][k]->C[i][j]};
```

```
Order := [n]->{S[i][j]->[i][j][0]; T[i][j][k]->[i][j][1][k]};
```

Polyhedral model: ambiguity with the word “model”.

- Programming/specification model: • Feautrier’s model, Alpha, CRP
- Set of provable techniques under some hypotheses: • SCoP.
- **Simplified specification for extracting more general facts.**
 - Principle: study a polyhedral subset of a specification/language.

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Examples:

- Uniform loops (simple case to discuss NP-completeness).
- Polyhedral X10 (Yuki, Feautrier, Rajopadhye, Saraswat, PPOPP’13).
- Polyhedral OpenStream (this talk).

Analyzing X10 through a polyhedral fragment

X10 language developed at IBM, variant at Rice (V. Sarkar)

- PGAS (partitioned global address space) memory principle.
- Parallelism of threads: in particular keywords **finish**, **async**, **clock**.
- No deadlocks by construction but non-determinism.

Polyhedral X10 Yuki, Feautrier, Rajopadhye, Saraswat (PPoPP 2013)

Can we analyze the code for data races?

```
finish {  
  for(i in 0..n-1) {  
    S1;  
    async {  
      S2;  
    }  
  }  
}
```

```
clocked finish {  
  clocked async {  
    S1;  
    advance();  
  }  
  S2;  
  advance();  
}
```

Polyhedral X10 dependence analysis

Let $W : A[f(\vec{x})] = \dots$ be a write and $R : \dots = A[g(\vec{y})]$ a read in array A .

Imperative sequential code (total order)

- \prec : disjunction of affine conjunctions (lexicographic order).
 - Find the maximal \vec{x} , w.r.t. \prec , such that:
 - \vec{x} and \vec{y} are legal iterations $\vec{x} \in D_W; \vec{y} \in D_R$.
 - W and R access the same element of A : $f(\vec{x}) = g(\vec{y})$.
 - $\vec{x} \prec \vec{y}$.
- ☛ Maximization, gives exact dependence analysis (Feautrier IJPP 1991).

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Polyhedral X10 fragment (add just async: partial order)

- \prec can still be expressed as an incomplete lexicographic order.
- $\vec{x} \prec \vec{y}$ becomes $\neg(\vec{y} \prec \vec{x})$ and $\vec{x} \neq \vec{y}$.
- Maximization now builds a set of (non-comparable) extrema.
- W/W and R/W races can be checked similarly.

☛ Yuki, Feautrier, Rajopadhye, Saraswat (PPoPP 2013).

What about X10 clocks?

Assume a single clock

$\phi(\vec{x})$ “phase” number of \vec{x} : number of advances before \vec{x} .

➤ Depends only on \prec : can be expressed by polyhedral techniques.

Also, $\vec{x} \prec \vec{y} \Rightarrow \phi(\vec{x}) \leq \phi(\vec{y})$.

Clocks adds ordering constraints

➤ New partial order \prec_c : $\vec{x} \prec_c \vec{y}$ iff $\vec{x} \prec \vec{y}$ or $\phi(\vec{x}) < \phi(\vec{y})$.

Detection of races?

➤ Now becomes undecidable (Hilbert 10th problem), Feautrier (2013).

X10: expressiveness + deadlock-free \Rightarrow non-determinism + undecidability

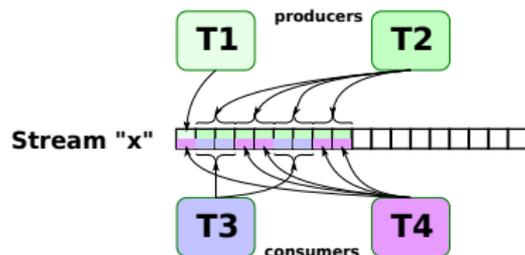
OpenStream: expressiveness + determinism \Rightarrow deadlocks + undecidability.

Analyzing OpenStream through a polyhedral fragment

```
#pragma omp task output (x) // Task T1
x = ...;
for (i = 0; i < N; ++i) {
  int window_a[2], window_b[3];

  #pragma omp task output (x < window_a[2]) // Task T2
  window_a[0] = ...; window_a[1] = ...;
  if (i % 2) {
    #pragma omp task input (x > window_b[2]) // Task T3
    use (window_b[0], window_b[1]);
  }
  #pragma omp task input (x) // Task T4
  use (x);
}
```

(Pop, Cohen, 2011)



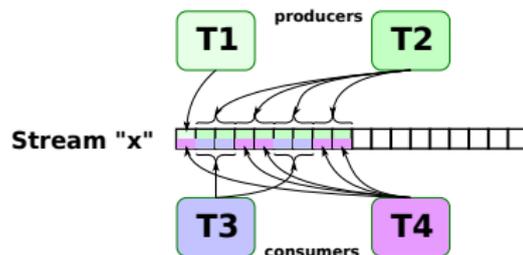
- Sequential control program for **task activations**.
- Reservation for reads/writes in **streams** with **burst** and **horizon**.
- **Single assignment** in streams (by construction) + **dataflow semantics**.

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- Sequential control program for **task activations**.
- Reservation for reads/writes in **streams** with **burst** and **horizon**.
- **Single assignment** in streams (by construction) + **dataflow semantics**.
- Instance of Pop-Cohen CDDF (Control-Driven Data Flow).
- Optimization in Erbium runtime system explored by Pop & Miranda.
- Unlike KPN, streams with multiple inputs/outputs (but deterministic).

Some properties of polyhedral OpenStream

- The order of activations is the sequential order of the control program.
- Access functions to streams are **statically-expressible polynomials**.
- Dependence analysis is feasible with tools manipulating polynomials.

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Deadlock characterization iff there is, in the unrolled dependence graph,

- a statement T and an **infinite sequence** $(i_j)_{j \in \mathbb{N}}$ such that $T(i_j)$ depends on $T(i_{j+1})$ and i_j is before i_{j+1} in the activation program;
- a **cycle** if the program is bounded or follows Kahnian semantics.

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Deadlock detection If access indices can express polynomials of large degrees, deciding the presence of deadlocks is **undecidable**, and one can build such an OpenStream program.

☛ **Consequence:** Not clear how to optimize, unless with polynomial computations (cf Feautrier, with Schweighofer/Handelman theorem).

First ingredient (Feautrier): build multivariate polynomials

$Q(x_1, \dots, x_n)$: multivariate polynomial, nonnegative integer coefficients.

Write:

- $Q(x) = Q(x_1, x_r)$, x_1 first variable.
- $Q^1(x_1, x_r) = Q(x_1 + 1, x_r) - Q(x_1, x_r)$ (first difference)
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phi = Q(0, x_r);  
for (i = 0; i < x; i++) {  
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- Keep going until x_1 disappears.

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for (i = 0; i < x; i++) {
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    for (j = 0; j < i; j++) {
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- Keep going until x_1 disappears.
- Continue with other variables:

```
phi = Q(0, x_r);  
for (i = 0; i < x; i++) {  
    // phi += Q1(i, x_r);  
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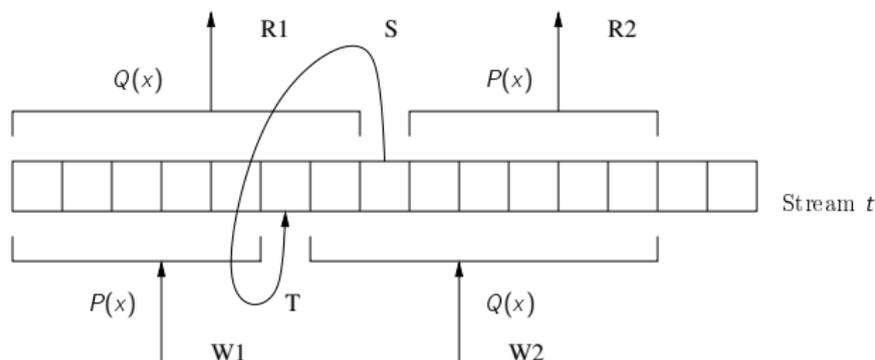
```
phi = Q(0, x_r); // Put new loops  
for (i = 0; i < x; i++) {  
    // phi += Q1(i, x_r);  
    phi += Q1(0, x_r); // Put new loops  
    for (j = 0; j < i; j++) {  
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    }  
}
```

Second ingredient: build the OpenStream structure

```
s, t streams;  
for (x in D) {  
  /* D is the n-dimensional cube  
   of size N in the first orthant */  
  R1: read Q(x) times in t;  
  W1: write P(x) times in t;  
  S: read once in t and write once in s;  
  T: read once in s and write once in t;  
  R2: read P(x) times in t;  
  W2: writes Q(x) times in t;  
}
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Deadlock situations:

- General case: iff $P(x) = Q(x)$.
- Kahnian case: iff $P(x) \leq Q(x)$.
Note: iff no **causal** schedule.

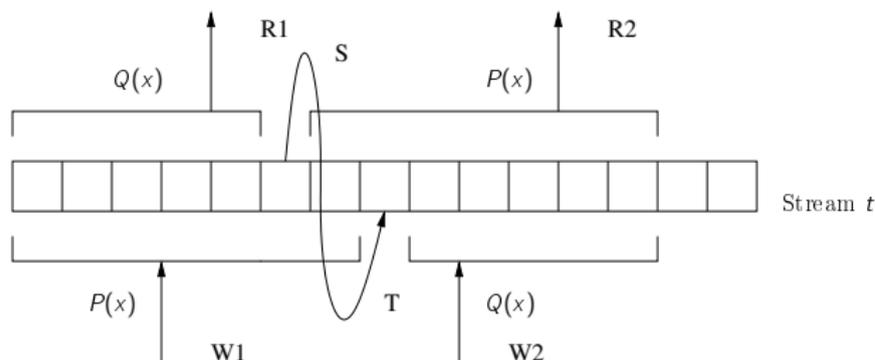


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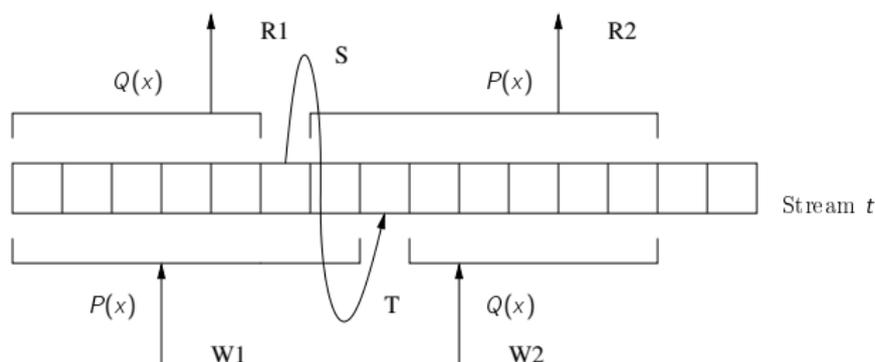
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10th Hilbert's problem:

- $R(x) = 0$ iff $R^+(x) = R^-(x)$.
- $R(x) = 0$ iff $R^2(x) \leq 0$.



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- But model can react on values in streams (not here).

Take-home messages

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About parallel languages

- What do you prefer: deadlocks or races?
 - How to express link between user/compiler and compiler/runtime?
 - Parallel constructs can help dependence analysis (cf V. Sarkar).
- ➡ Towards the analysis of parallel languages, with better user/compiler and compiler/runtime interactions.